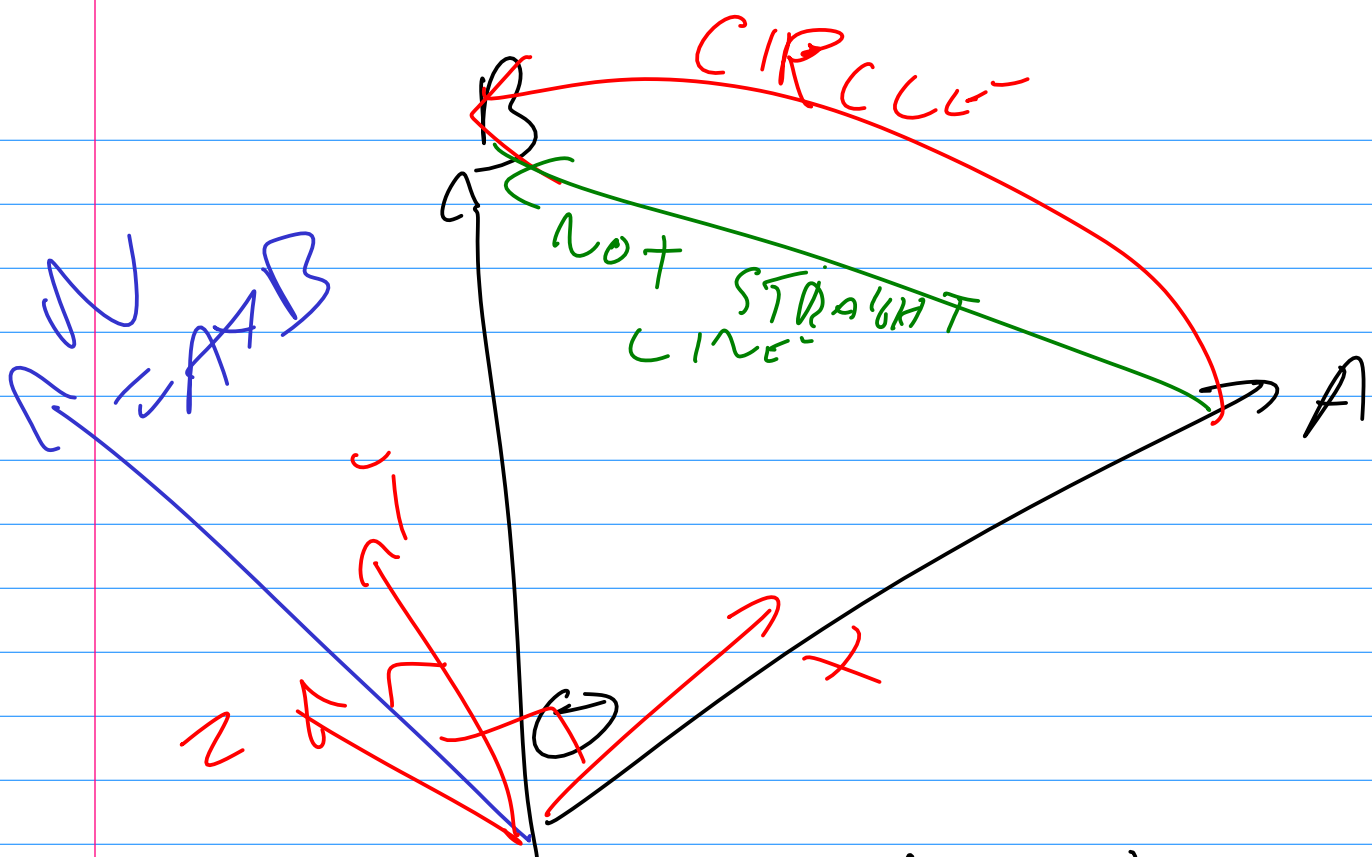


COMPUTE MATRIX M TO ROTATE
 $A \rightarrow B$ NEED M^{-1}



FIND θ : $A \cdot B = |A| |B| \cos \theta$
 IF $|A| = |B| = 1$ $\cos \theta = A \cdot B$

WE HAVE A 3D COORDINATE SYSTEM WITH

$A, \underline{N \times A}, N$

ROTATING AROUND N

$B =$

ROTATIONS IN 2D 3

POINT (x, y) $(3, 5)$ \rightarrow COMPLEX N.
 $z = x + iy$ $3 + 5i$

TRANSLATE BY (D_x, D_y) $(2, 1)$ $\rightarrow (D_x + 1, D_y)$

ROTATE BY θ

ABOUT ORIGIN $\rightarrow \times e^{i\theta}$

$\theta \sim$ RADIANS

ROTATE BY $90^\circ = \frac{\pi}{2}$

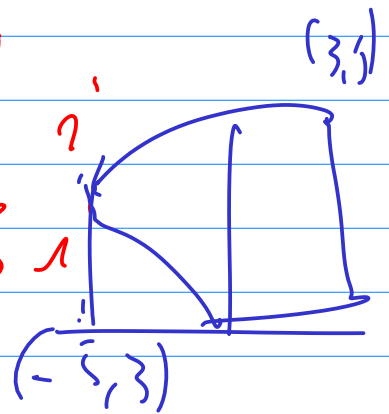
\rightarrow MULT BY $e^{i\frac{\pi}{2}} = i$

TO ROTATE $(3, 5)$ BY 90° ,

MULTIPLY $3 + 5i$ BY i

$$= 3i + 5i^2 = -5 + 3i$$

POINT $(-5, 3)$



WE CAN EASILY COMBINE OPS I WANT TO

1. TRANS BY (1,2)

2 ROTATE BY 90°

3 TRANS BY (3,4)

4 SCALE BY 2

5 ROTATE BY 180° = π (e^{iπ} = -1)

z' = 2 ((z + (1+2i))i + (3+4i))

1z + (-2+2i)
1z + (-2-10i)

z' = -2z + (-2-10i)

- z 90° ROT
+ SCALE BY -2
+ TRANS BY (-2, -10)

Using complex numbers for 2D points lets you simplify a long string of translations, rotations, and scalings down to one scaling, one rotation, and then one translation.

Hamilton wanted a 3D analog to complex numbers.

Problem: 3D rotations don't commute.

$$Q = a + bI + cJ + dK$$

REAL NUMBERS
INDETERMINATES

SIMPLIFY COMBS OF I, J, K .

$$I^2 = J^2 = K^2 = -1$$

$$IJ = K \quad JK = I \quad KI = J$$

$$JI = -K \quad KJ = -I \quad IK = -J$$

$$Q_1 = 1 + 2I + 3J + 4K$$

$$Q_2 = 5 + 6I + 7J + 8K$$

$$Q_1^{-1}Q_2 = 6 + 8I + 10J + 12K$$

$$7Q_1 = 7 + 14I + 21J + 28K$$

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$$Q_1 = 1 + 2a$$

$$Q_2 = 3J + 4K$$

$$Q_1 Q_2 = (1 + 2a)(3J + 4K)$$

$$= 3J + 4K + 6aJ + 8aK$$

$$= 3J + 4K + 6K - 8J$$

$$= -5J + 10K$$

POINT (1, 0, 2)

$$P = 1 + 2k$$

ROT BY 90° ABOUT X AXIS

$$Q = .7 + .7i$$

$$P' = (.7 + .7i) P (.7 - .7i)$$

$$= (.7 + 1.4k - .7 - 1.4j) (.7 - .7i)$$

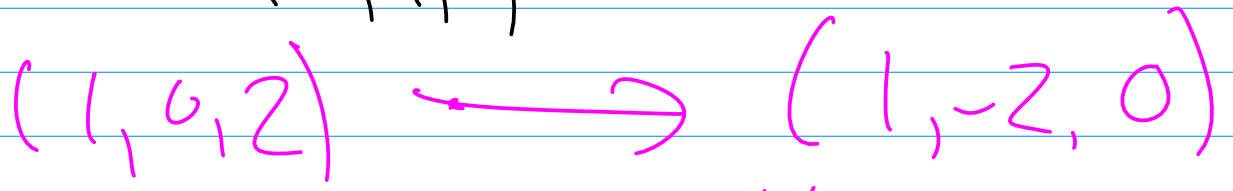
$$= .5 (1 + 2k - 1 - 2j) (1 - i)$$

$$= .5 (-1 + i - 2j + 2k) (1 - i)$$

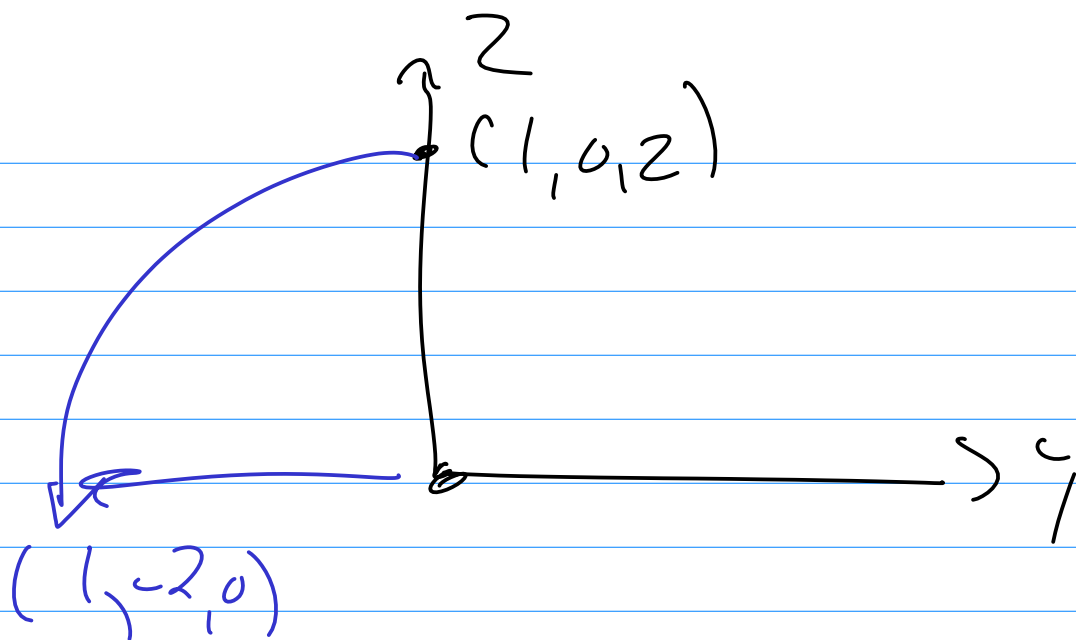
$$= .5 (-1 + i - 2j + 2k + i + 1 - 2k + 2j)$$

$$= .5 (5i - 4j) = (-1 - 2j)$$

POINT (1, -2, 0)



90° ABOUT X AXIS



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WHAT IS COMB OTC
 90° ABOUT X THEN
 90° ABOUT Y ?

$$Q_1 = \dots \dots \dots (1+1)$$

$$Q_2 = \dots (1+J)$$

$$Q = Q_1 Q_2 = \dots (1+1) \dots (1+J)$$

$$= .5 (1+1 + J + \cancel{1J})$$

$$= .5 + .5 (1+J+K)$$

FINAL ROTATION

$$Q = .5 + .5 (i + j + k)$$

cos θ \uparrow

$$\frac{\theta}{2} = 60^\circ$$

$$\theta = 120^\circ$$

$$\frac{\sqrt{3}}{2} \left(\frac{i + j + k}{\sqrt{3}} \right)$$

$$120^\circ \text{ ABOUT } \left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right)$$